

### **Data Sheet**

## R-Series V RFV Analog Magnetostrictive Linear Position Sensors

- Flexible sensor rod
- Stroke length up to 20 m
- Field adjustments and diagnostics using the new TempoLink® smart assistant



### MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

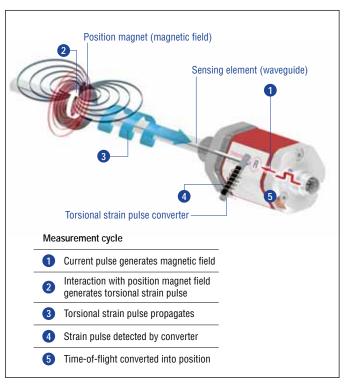


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

### R-SERIES V RFV Analog

The Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The RFV sensor is the R-Series V with flexible rod. The main advantages of the flexible rod are:



### Straight and curved line

The flexible measuring rod enables position measurement on straight and also curved line.



### Compact for transport and storage

For transport and storage, the RFV sensor can be coiled up. This saves costs and space.



### Installation with little space

Due to the bendable rod, the RFV sensor can be installed even if only little space is available.



### Large stroke length range

The sensor is available with stroke lengths from 150 mm to 20,000 mm and thus can be used in both short and long distance applications.

In addition the R-Series V Analog scores with the following features:



### 2 positions simultaneously

The R-Series V Analog can detect and report the position of up to 2 magnets simultaneously.



### R-Series V Analog

With the R-Series V Analog you can configure the Analog output (current/voltage) that it fits best for your application and also adjust it on site with the sensor assistant.

All settings under control with the sensor assistant for the R-Series V The TempoLink® smart assistant supports you in setup and diagnostics of the R-Series V. For more information of the assistant please see the data sheet:

 TempoLink® smart assistant (<u>Document part number: 552070</u>)



### **TECHNICAL DATA**

Output									
Analog	Voltage: 010 /100/–10+10/+10–10 VDC (min. controller load > 5 kΩ) Current: 4(0)20/204(0) mA (min./max. load 0/500 Ω)								
Measured output variables	Position for one or two position magnets Position + speed (without direction) or velocity (with direction) for one position magnet Position for one position magnet + temperature inside the sensor electronics housing								
Measurement parameters	1 contain for the position magnet i temperature mende the contest check of the deling								
Position measurement									
Null/Span adjustment	100 % of electrical stroke								
Resolution	16 bit (internal resolution 0.1 μm)								
Update time	Stroke length         ≤ 200 mm         ≤ 350 mm         ≤ 1200 mm         ≤ 2400 mm         ≤ 4800 mm         ≤ 7620 mm         ≤ 10,000 mm         ≤ 20,000 mm           Update time         0.25 ms         0.333 ms         0.5 ms         1.0 ms         2.0 ms         5.0 ms         7.5 ms         15.0 ms								
Linearity deviation <sup>1</sup>	< ±0.02 % F.S. (minimum ±100 μm)								
Repeatability	$<\pm0.001$ % F.S. (minimum $\pm2.5$ $\mu$ m) typical								
Hysteresis	< 4 μm typical								
Temperature coefficient	< 30 ppm/K typical								
Velocity measurement									
Range	0.0110 m/s or 1400 in./s								
Deviation	≤ 0.05 %								
Resolution	16 bit (minimum 0.01 mm/s)								
Operating conditions									
Operating temperature	-40+85 °C (-40+185 °F)								
Humidity	90 % relative humidity, no condensation								
Ingress protection	IP30 (IP65 rating only for professional mounted guide pipe and if mating connectors are correctly fitted)								
Shock test	100 g/6 ms IEC standard 60068-2-27								
Vibration test	5 g/102000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)								
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The RFV sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011 under the condition of an EMC compliant installation <sup>2</sup>								
Magnet movement velocity	Any								
Design/Material									
Sensor electronics housing	Aluminum (painted), zinc die cast								
Sensor flange	Stainless steel 1.4305 (AISI 303)								
Sensor rod	Stainless steel conduit with PTFE coating								
RoHS compliance	The used materials are compliant with the requirements of EU Directive 2011/65/EU and EU Regulation 2015/863 as well as UKSI 2022 No. 622								
Stroke length	te length 15020,000 mm (6787 in.)								
Mechanical mounting									
Mounting position	Any								
Mounting instruction	Please consult the technical drawings on page 5 and page 6 and the operation manual (document part number: 552063)								

Technical data "Electrical connection" on page 4

<sup>1/</sup> With position magnet # 251 416-22/ The flexible sensor element must be mounted in an appropriately shielded environment

### Temposonics® R-Series V RFV Analog Data Sheet

Electrical connection	
Connection type	1 × M16 male connector (6 pin) or 1 × M12 male connector (5 pin) or cable outlet
Operating voltage	1230 VDC ±20 % (9.636 VDC)
Power consumption	< 3.25 W
Dielectric strength	500 VDC (DC ground to machine ground)
Polarity protection	Up to –36 VDC
Overvoltage protection	Up to 36 VDC

### **TECHNICAL DRAWING**

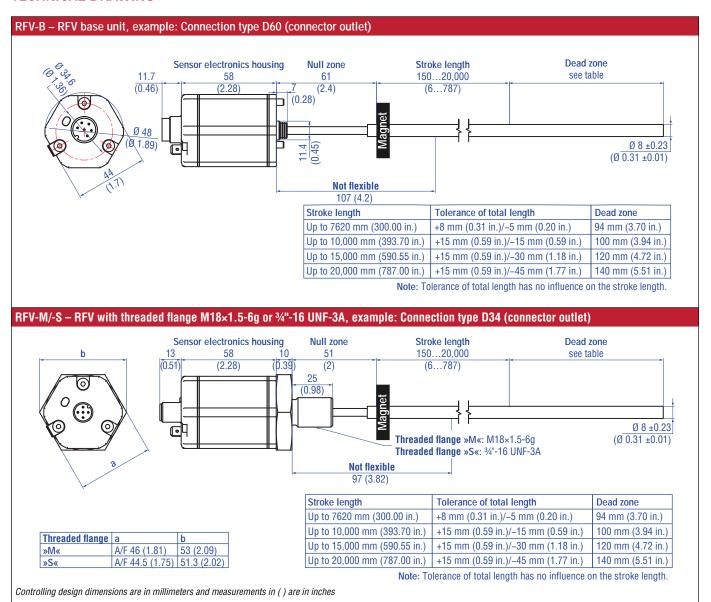


Fig. 2: Temposonics\* RFV with ring magnet, part 1

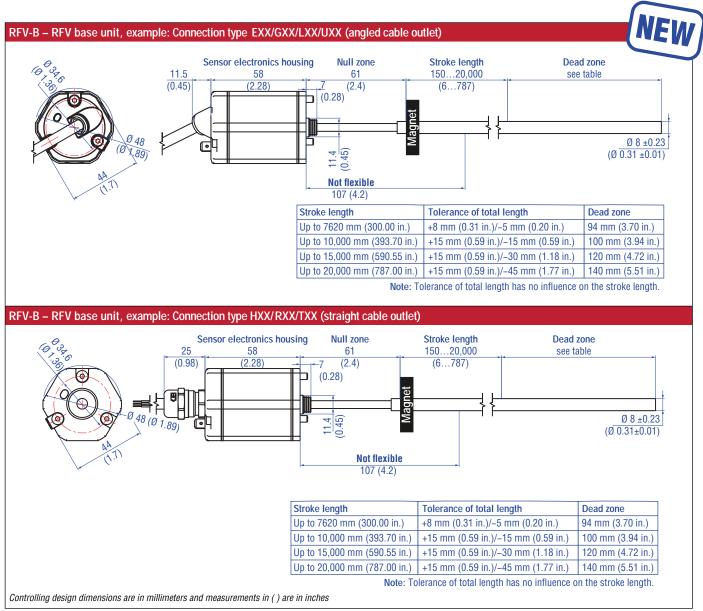


Fig. 3: Temposonics\* RFV with ring magnet, part 2

### **CONNECTOR WIRING**

D34									
Signal + power supply									
M12 male connector Output Pin Function									
	1	1	+1230 VDC (±20 %)						
	'	2	Position (magnet 1)						
0		3	DC Ground (0 V)						
View on sensor	2*	4	Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or temperature inside the sensor electronics housing						
		5	Signal Ground						
			* order dependent						

Fig. 4: Connector wiring D34

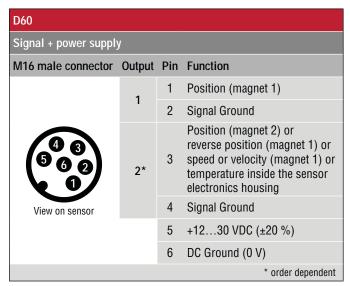


Fig. 5: Connector wiring D60

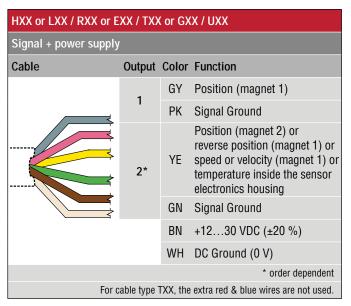


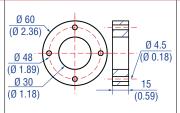
Fig. 6: Connector wiring cable outlet

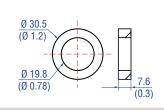
Str	aigh	t ca	ble outlet	Cable	e type	Ano	gled	cab	le outlet
Н	Х	Х	Part no. 530 052	PUR	<b>→</b>	L	Х	Х	Part no. 530 052
R	Х	Х	Part no. 530 032	PVC	<b>→</b>	Ε	Х	Х	Part no. 530 032
Т	Х	Х	Part no. 530 112	FEP	<b>→</b>	G	Х	Х	Part no. 530 157

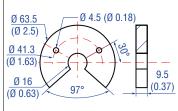
Fig. 7: Cable types assignment

### FREQUENTLY ORDERED ACCESSORIES – Additional options available in our Accessories Catalog 3551444

# Position magnets Ø 4.3 Ø 0.17) Ø 23.8 Ø 1.29) Ø 23.8 Ø 0.94) Ø 13.5 Ø 0.94) Ø 13.5 Ø 0.53)







### U-magnet OD33 Part no. 251 416-2

Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm<sup>2</sup> Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)

### Ring magnet OD60 Part no. MT0162

Material: AlCuMgPb, magnets compound-filled Weight: Approx. 90 g Surface pressure: Max. 20 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+75 °C (-40...+167 °F)

### Ring magnet Part no. 402 316

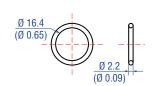
Material: PA ferrite coated Weight: Approx. 13 g Surface pressure: Max. 20 N/mm<sup>2</sup> Operating temperature: -40...+100 °C (-40...+212 °F)

#### U-magnet 0D63.5 Part no. 201 553

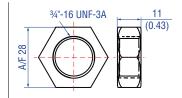
Material: PA 66-GF30, magnets compound-filled Weight: Approx. 26 g Surface pressure: 20 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+75 °C (-40...+167 °F)

### 0-rings

### Ø 15.3 (Ø 0.6) Ø 2.2 (Ø 0.09)



# M18×1.5-6g (0.34)



### O-ring for threaded flange M18×1.5-6g Part no. 401 133

Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)

### O-ring for threaded flange 3/4"-16 UNF-3A Part no. 560 315

Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)

### Hex jam nut M18×1.5-6g Part no. 500 018

Mounting accessories

Material: Steel, zinc plated

### Hex jam nut ¾"-16 UNF-3A Part no. 500 015

Material: Steel, zinc plated

### Mounting accessories





### Threaded flange M18×1.5-6g Part no. 404 874

Material: Stainless steel 1.4305 (AISI 303)

### Threaded flange ¾"-16 UNF-3A Part no. 404 875

Material: Stainless steel 1.4305 (AISI 303)

### Mounting accessories



Pressure rod with threaded flange with flat-face (M18×1.5-6g) and O-ring

HD [length mm: XXXX] M
HD [length in.: XXX.X] U

Pressure rod Ø: 12.7 mm (0.5 in.) Length: 100...7500 mm (4...295 in.) Operating pressure: 350 bar (5076 psi) Material flange:

Stainless steel 1.4305 (AISI 303) Material rod:

Stainless steel 1.4301 (AISI 304)



Pressure rod with threaded flange with flat-face (¾"-16 UNF-3A) and O-ring

HL [length mm: XXXX] M
HL [length in.: XXX.X] U

Pressure rod Ø: 12.7 mm (0.5 in.) Length: 100...7500 mm (4...295 in.) Operating pressure: 350 bar (5076 psi)

Material flange: Stainless steel 1.4305 (AISI 303)

Material rod:

Stainless steel 1.4301 (AISI 304)



Profile with flange

HFP [length mm: XXXXXX] M
HFP [length in.: XXXX.X] U

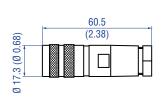
Length: Max. 20 000 mm (max. 787 in.)

Ingress protection: IP30 Material: Aluminum

### Temposonics® R-Series V RFV Analog

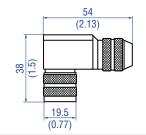
#### Data Sheet

### Cable connectors\*



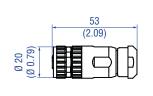
### M16 female connector (6 pin), straight Part no. 370 423

Material: Zinc nickel plated Termination: Solder Cable Ø: 6...8 mm (0.24...0.31 in.) Operating temperature: -40...+100 °C (-40...+212 °F) Ingress protection: IP65/IP67 (correctly fitted) Fastening torque: 0.6 Nm



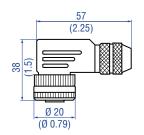
### M16 female connector (6 pin), angled Part no. 370 460

Material: Zinc nickel plated Termination: Solder Cable Ø: 6...8 mm (0.24...0.31 in.) Wire: 0.75 mm² (20 AWG) Operating temperature: -40...+95 °C (-40...+203 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.6 Nm



### M12 A-coded female connector (4 pin/5 pin), straight Part no. 370 677

Material: GD-Zn, Ni
Termination: Screw
Contact insert: CuZn
Cable Ø: 4...8 mm (0.16...0.31 in.)
Wire: 1.5 mm²
Operating temperature:
-30...+85 °C (-22...+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.6 Nm



### M12 A-coded female connector (5 pin), angled Part no. 370 678

Material: GD-Zn, Ni Termination: Screw; max. 0.75 mm² Contact insert: CuZn Cable Ø: 5...8 mm (0.2...0.31 in.) Wire: 0.75 mm² (18 AWG) Operating temperature: -25...+85 °C (-13...+185 °F) Ingress protection: IP67 (correctly fitted) Fastening torque: 0.4 Nm

#### Cables



### PVC cable Part no. 530 032

Material: PVC jacket; gray Features: Twisted pair, shielded, flexible Cable Ø: 6 mm (0.23 in.) Cross section:  $3 \times 2 \times 0.14$  mm<sup>2</sup> Bending radius:  $10 \times D$  (fixed installation) Operating temperature: -40...+105 °C (-40...+221 °F)



### PUR cable Part no. 530 052

Material: PUR jacket; orange Features: Twisted pair, shielded, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant Cable Ø: 6.4 mm (0.25 in.) Cross section:  $3 \times 2 \times 0.25 \text{ mm}^2$  Bending radius:  $5 \times D$  (fixed installation) Operating temperature: -30...+80 °C (-22...+176 °F)



### FEP cable Part no. 530 112

Material: FEP jacket; black Features: Twisted pair, shielded, flexible, high thermal resistance, mostly oil & acid resistant Cable Ø: 7.6 mm (0.3 in.) Cross section:  $4 \times 2 \times 0.25$  mm² Bending radius:  $8-10 \times D$  (fixed installation) Operating temperature: -100...+180 °C (-148...+356 °F)



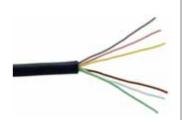
### FEP cable Part no. 530 157

Material: FEP jacket; black Features: Twisted pair, shielded Cable Ø: 6.7 mm (0.26 in.) Cross section:  $3 \times 2 \times 0.14$  mm<sup>2</sup> Operating temperature: -100...+180 °C (-148...+356 °F)

<sup>\*/</sup> Follow the manufacturer's mounting instructions Controlling design dimensions are in millimeters and measurements in ( ) are in inches

### Cables

### Cable sets



### Silicone cable Part no. 530 176

Material: Silicone jacket; black Features: Twisted pair, shielded Cable Ø: 6.3 mm (0.25 in.) Cross section:  $3 \times 2 \times 0.14 \text{ mm}^2$ Bending radius: 7 x D (fixed installation) Operating temperature: -50...+150 °C (-58...+302 °F)



### Cable with M12 A-coded female connector (5 pin), straight - pigtail Part no. 370 673

Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67 (correctly fitted) Operating temperature: -25...+80 °C (-13...+176 °F)



Cable with M12 A-coded female connector (5 pin), angled - pigtail Part no. 370 675

Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67 (correctly fitted) Operating temperature: -25...+80 °C (-13...+176 °F)

### **Programming tools**







### Hand programmer for analog output Part no. 253 124

### Cabinet programmer for analog output TempoLink® kit for Temposonics® Part no. 253 408

Easy teach-in-setups of stroke length and direction on desired zero / span positions. For sensors with 1 magnet. Features snap-in mounting on standard DIN rail (35 mm). This programmer can be permanently mounted in a control cabinet and includes a program/run switch. For sensors with 1 magnet.

R-Series V

Part no. TL-1-0-AD60 (for D60) Part no. TL-1-0-AS00 (for cable outlet) Part no. TL-1-0-AD34 (for D34)

- · Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic
- Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m)
- User friendly interface for mobile devices and desktop computers
- See data sheet "TempoLink® smart assistant" (document part no.: 552070) for further information

Controlling design dimensions are in millimeters and measurements in ( ) are in inches Color of connectors and cable jacket may change. Colors of the cores and technical properties remain unchanged.

### **Extension cables**



### PVC cable with M16 female connector (6 pin), straight – pigtail

PVC cable (part no. 530 032) with M16 female connector, straight (part no. 370 423)

Order code:

K2-A-370423-xxxxyy-530032-0 (where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



### PUR cable with M16 female connector (6 pin), straight – pigtail

PUR cable (part no. 530 052) with M16 female connector, straight (part no. 370 423)

Order code:

**K2-A-370423-xxxxyy-530052-0** (where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



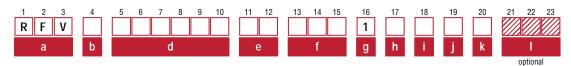
Teflon® cable with M16 female connector (6 pin), straight – pigtail

FEP cable (part no. 530 112) with M16 female connector, straight (part no. 370 423)

Order code:

K2-A-370423-xxxxyy-530112-0 (where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")

### **ORDER CODE**



#### a Sensor model

R F V Flexible rod

### b Design

- B Base unit
- M Threaded flange M18×1.5-6g (standard)
- S Threaded flange 3/4"-16 UNF-3A (standard)

Section c is intentionally omitted.

### d Stroke length

X X X X X M 0015020000			ĺ	)	K		l	ı		Χ				Χ		l	)	(		X	(		N	1	0	0.	15	50	).		2	0(	)(	)(	0	n	٦I	Υ
------------------------	--	--	---	---	---	--	---	---	--	---	--	--	--	---	--	---	---	---	--	---	---	--	---	---	---	----	----	----	----	--	---	----	----	----	---	---	----	---

Ordering steps	
50 mm	
100 mm	
250 mm	
500 mm	
1000 mm	
	50 mm 100 mm 250 mm 500 mm

X X X X X U 0006.0...0787.0 in.

Stroke length (in.)	Ordering steps
6 40 in.	2 in.
40197 in.	4 in.
197394 in.	10 in.
394591 in.	20 in.
591787 in.	40 in.

Non standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments

### e Number of magnets

0 X 01...02 Position(s) (1...2 magnet(s))

### f | Connection type

### Connector

- D 3 4 M12 male connector (5 pin)
- D 6 0 M16 male connector (6 pin)

### Angled cable outlet

- E X XX m/ft. PVC cable (part no. 530 032) E01...E30 (1...30 m/3...99 ft.) See "Frequently ordered accessories" for cable specifications
- G X XX m/ft. FEP cable (part no. 530 157)
  G01...G30 (1...30 m/3...99 ft.)
  See "Frequently ordered accessories" for cable specifications
- XX m/ft. PUR cable (part no. 530 052)
  L01...L30 (1...30 m/3...99 ft.)
  (Note the temperature range of the cable!)
  See "Frequently ordered accessories" for cable specifications
- U X X XX m/ft. Silicone cable (part no. 530 176)
  U01...U30 (1...30 m/3...99 ft.)
  See "Frequently ordered accessories" for cable specifications

### Straight cable outlet

- H X X XX m/ft. PUR cable (part no. 530 052)
  H01...H30 (1...30 m/3...99 ft.)
  (Note the temperature range of the cable!)
  See "Frequently ordered accessories" for cable specifications
- R X XX m/ft. PVC cable (part no. 530 032)
  R01...R30 (1...30 m/3...99 ft.)
  See "Frequently ordered accessories" for cable specifications
- T X XX m/ft. FEP cable (part no. 530 112)
  T01...T30 (1...30 m/3...99 ft.)
  See "Frequently ordered accessories" for cable specifications

Encode in meters if using metric stroke length. Encode in feet if using US customary stroke length.

### g System

1 Standard

### h Output

A Current

V Voltage

### Temposonics® R-Series V RFV Analog

Data Sheet

### i Function

- 1 Position (1 or 2 magnets/outputs)
- 2 Position and speed (1 magnet and 2 outputs)
- 3 Position and velocity (1 magnet and 2 outputs)
- 4 Position and reverse position (1 magnet and 2 outputs)
- Position and temperature inside the sensor electronics housing (1 magnet and 2 outputs)
- 6 Differential (2 magnets and 1 output)

### j Options

- 0 Standard
- 3 Over range output mode

### k Output range

- 0 0...10 VDC or 4...20 mA
- 1 10...0 VDC or 20...4 mA
- 2 -10...+10 VDC or 0...20 mA
- 3 +10...-10 VDC or 20...0 mA
- V 0...10 VDC for position, -10...+10 VDC for velocity

### I Max speed or velocity value

### (optional: use when i "Function" is 2 or 3)

For metric stroke lengths encode speed or velocity in m/s for the values 0.01 to 9.99 m/s (001...999)

For US customary stroke lengths encode speed or velocity in inches/s for the values 1 to 400 in./s (001...400)

Use the codes (00E) for 0.025 m/s, and (A00) for 10.0 m/s to provide backwards compatibility for these predecessor models of the R-Series.

### NOTICE

- Specify the number of magnets for your application and order the magnets separately.
- The number of magnets is limited by the stroke length.
   The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for multi-position measurement.

### **DELIVERY**



#### RFV-B

- Base unit (without flange & rod assembly)
- 3 × socket screws M4×59

### RFV-M/-S:

- Sensor
  - 0-ring

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at: www.temposonics.com

### **GLOSSARY**

#### Α

### **Analog output**

For a sensor with analog output, the measured value is output as an analog voltage signal or current signal.

#### D

### Differential

For differential measurement, the distance between the two position magnets is output as a value.

(→ Multi-position measurement)

#### М

### Max speed or velocity value

For speed or velocity, the output value generated is scaled based on the maximum speed or velocity value indicated in the order code.

### Measuring direction

- Forward: Values increasing from sensor electronics housing to rod end/profile end
- Reverse: Values decreasing from sensor electronics housing to rod end/profile end

### Multi-position measurement

During the measurement cycle, the positions of every magnet on the sensor are simultaneously reported. The velocity or speed are continuously calculated based on these changing position values as the magnets are moved.

#### 0

### Over range output mode

When enabled this mode allows the position output values to continue to increase or decrease when the magnet travels beyond the active stroke range.

### R

#### Resolution

The sensor precisely measures time to provide the position measurement. For the analog output the measured time value is converted into an analog voltage signal or current signal using a high-performance Digital to Analog Converter (DAC) having 16 bits of resolution.

### S

### **Speed**

The output value for speed indicates how fast the position magnet is being moved, independent of the measuring direction. ( $\rightarrow$  Velocity)

#### т

### Temperature inside the sensor electronics housing

The temperature inside the sensor electronics housing is reported as an analog voltage signal or current signal. For each output range, the 0 % output value has the factory default setpoint at -40 °C, and the 100 % output value has the default setpoint at +100 °C. Note: a dedicated temperature chip is used for the output signal and its values may vary from those reported on the TempoLink® application screen.

### ٧

### Velocity

The output value for velocity indicates how fast the position magnet is being moved, and in which direction.  $(\rightarrow Speed)$ 



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