

Data Sheet

R-Series V RH5 Analog

Magnetostrictive Linear Position Sensors

- Output of position and speed/velocity
- Dual magnet position measurement
- Field adjustments and diagnostics using the TempoLink® smart assistant



MEASURING TECHNOLOGY

The absolute, linear position sensors provided by Temposonics rely on the company's proprietary magnetostrictive technology, which can determine position with a high level of precision and robustness. Each Temposonics® position sensor consists of a ferromagnetic waveguide, a position magnet, a strain pulse converter and a supporting electronics. The magnet, connected to the object in motion in the application, generates a magnetic field at its location on the waveguide. A short current pulse is applied to the waveguide. This creates a momentary radial magnetic field and torsional strain on the waveguide. The momentary interaction of the magnetic fields releases a torsional strain pulse that propagates the length of the waveguide. When the ultrasonic wave reaches the beginning of the waveguide it is converted into an electrical signal. Since the speed of the ultrasonic wave in the waveguide is precisely known, the time required to receive the return signal can be converted into a linear position measurement with both high accuracy and repeatability.

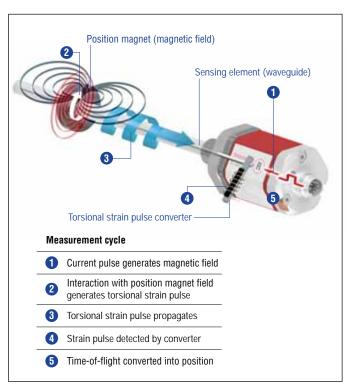


Fig. 1: Time-of-flight based magnetostrictive position sensing principle

R-SERIES ∨ RH5 Analog

The Temposonics® R-Series V brings very powerful sensor performance to meet the many demands of your application. The main advantages of the rod version RH5 with Analog output (current/voltage) are:



High shock and vibration resistance

The R-Series V is the long term solution for harsh environments that have high levels of shock and vibration.



Internal resolution 0.1 µm

The sensor works with an internal resolution of 0.1 μm to detect and report smallest position changes.



Dual output channel

The sensor is available with single output channel or with dual output channels.



Multiple output options

The following values can be output via the second output:

- Speed/velocity of the first magnet
- · Reversed position of the first magnet
- Position of the second magnet
- Temperature in the sensor electronics housing

In addition the R-Series V Analog scores with the following features:



2 positions simultaneously

The R-Series V Analog can detect and report the position of up to 2 magnets simultaneously.



R-Series V Analog

With the R-Series V Analog you can configure the Analog output (current/voltage) for your application and also adjust it on site with the smart assistant.

All settings under control with the smart assistant for the R-Series V

The TempoLink® smart assistant supports you in setup and diagnostics of the R-Series V. For more information of the assistant please see the data sheet:

 TempoLink® smart assistant (Document part number: <u>552070</u>)



TECHNICAL DATA

Output							
Analog	Voltage: 010 /100/ $-10+10/+1010$ VDC (min. controller load > 5 kΩ) Current: 4(0)20/204(0) mA (min./max. load 0/500 Ω)						
Measured output variables	Position for one or two position magnets Position + speed (without direction) or velocity (with direction) for one position magnet Position for one position magnet + temperature inside the sensor electronics housing						
Measurement parameters							
Position measurement							
Null/Span adjustment	100 % of electrical stroke						
Resolution	16 bit (internal resolution 0.1 µm)						
Update time	Stroke length ≤ 200 mm ≤ 350 mm ≤ 1200 mm ≤ 2400 mm ≤ 4800 mm ≤ 7620 mm						
	Update time 0.25 ms 0.333 ms 0.5 ms 1.0 ms 2.0 ms 5.0 ms						
Linearity deviation ¹	< ±0.01 % F.S. (minimum ±50 μm)						
Repeatability	< ±0.001 % F.S. (minimum ±1 μm)						
Hysteresis	< 4 μm typical						
Temperature coefficient	< 30 ppm/K typical						
Speed/velocity measurement	L Control of the Cont						
Range	0.0110 m/s or 1400 in./s						
Deviation	≤ 0.05 %						
Resolution	16 bit (minimum 0.01 mm/s)						
Operating conditions							
Operating temperature	-40+85 °C (-40+185 °F)						
Humidity	90 % relative humidity, no condensation						
Ingress protection	IP67 (connectors correctly fitted)/IP68 (3 m/3 d) for cable outlet						
Shock test	150 g/11 ms, IEC standard 60068-2-27						
Vibration test	30 g/102000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)/ RH5-J: 15 g / 102000 Hz, IEC standard 60068-2-6 (excluding resonant frequencies)						
EMC test	Electromagnetic emission according to EN 61000-6-3 Electromagnetic immunity according to EN 61000-6-2 The RH5 sensors fulfill the requirements of the EMC directives 2014/30/EU, UKSI 2016 No. 1091 and TR CU 020/2011						
Operating pressure	350 bar (5,070 psi)/700 bar (10,150 psi) peak (at 10 × 1 min) for sensor rod/RH5-J: 800 bar (11,600 psi)						
Magnet movement velocity	ty Any						
Design/Material							
Sensor electronics housing	Aluminum (painted), zinc die cast						
Sensor flange	Stainless steel 1.4305 (AISI 303)						
Sensor rod	Stainless steel 1.4306 (AISI 304L)/RH5-J: Stainless steel 1.4301 (AISI 304)						
RoHS compliance	The used materials are compliant with the requirements of EU Directive 2011/65/EU and EU Regulation 2015/863 as well as UKSI 2022 No. 622						
Stroke length	257620 mm (1300 in.)/RH5-J: 255900 mm (1232 in.)						
Mechanical mounting							
Mounting position	Any						
Mounting instruction	Please consult the technical drawings on page 5, page 6 and the operation manual (document part number: 552063)						

Technical data "Electrical connection" on page 4

^{1/} With position magnet # 251 416-2

Temposonics® R-Series V RH5 Analog

Data Sheet

Electrical connection	
Connection type	1 × M16 male connector (6 pin), 1 × M12 male connector (5 pin) or cable outlet
Operating voltage	1230 VDC ±20 % (9.636 VDC)
Power consumption	< 3.25 W
Dielectric strength	500 VDC (DC ground to machine ground)
Polarity protection	Up to –36 VDC
Overvoltage protection	Up to 36 VDC

TECHNICAL DRAWING

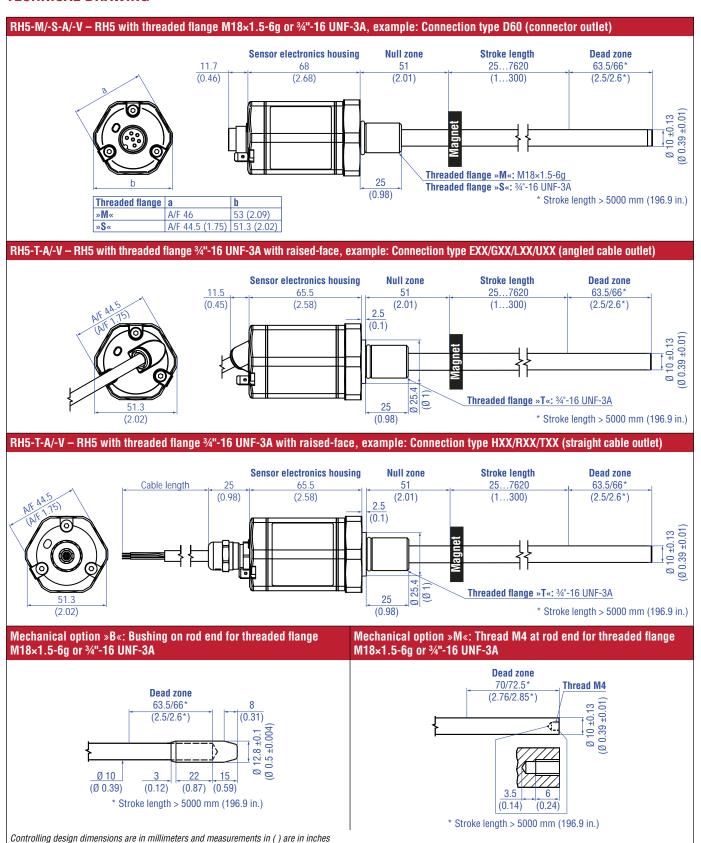


Fig. 2: Temposonics® RH5 with ring magnet, part 1

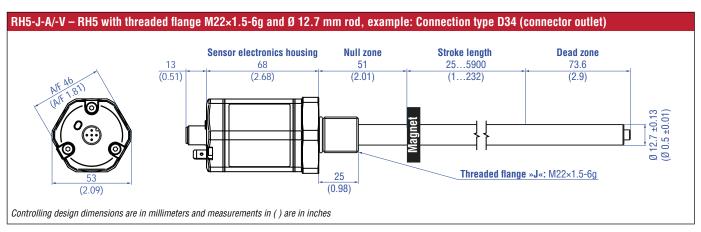


Fig. 3: Temposonics® RH5 with ring magnet, part 2

CONNECTOR WIRING

D34						
Signal + power supply						
M12 male connector	Output	Pin	Function			
		1	+1230 VDC (±20 %)			
	1	2	Position (magnet 1)			
0		3	DC Ground (0 V)			
View on sensor	2*	4	Position (magnet 2) or reverse position (magnet 1) or speed or velocity (magnet 1) or temperature inside the sensor electronics housing			
		5	Signal Ground			
			* order dependent			

Fig. 4: Connector wiring D34

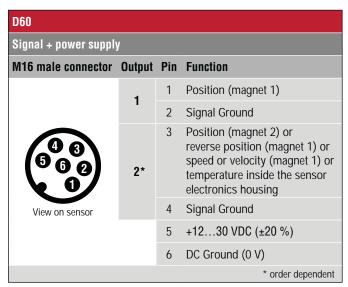


Fig. 5: Connector wiring D60

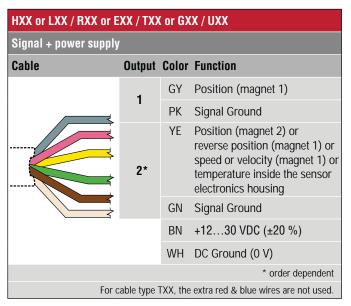


Fig. 6: Connector wiring cable outlet

NOTICE

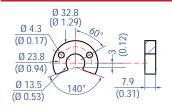
For sensors with current output (order code section **h** Output **A** Current), the output 1 (position (magnet 1)) must be connected in any case.

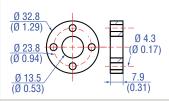
Straight cable outlet		Cable type Angle		jled	l cable outlet					
H	ł	X	X	Part no. 530 052	PUR	→	L	X	X	Part no. 530 052
F	}	X	X	Part no. 530 032	PVC	→	Ε	X	X	Part no. 530 032
	Γ	X	X	Part no. 530 112	FEP	→	G	X	X	Part no. 530 157

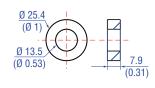
Fig. 7: Cable types assignment

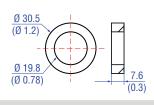
FREQUENTLY ORDERED ACCESSORIES - Additional options available in our Accessories Catalog 551444

Position magnets









U-magnet OD33 Part no. 251 416-2

Material: PA ferrite GF20 Weight: Approx. 11 g Surface pressure: Max. 40 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)

Ring magnet OD33 Part no. 201 542-2

Material: PA ferrite GF20 Weight: Approx. 14 g Surface pressure: Max. 40 N/mm² Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+105 °C (-40...+221 °F)

Ring magnet OD25.4 Part no. 400 533

Material: PA ferrite Weight: Approx. 10 g Surface pressure: Max. 40 N/mm² Operating temperature: -40...+105 °C (-40...+221 °F)

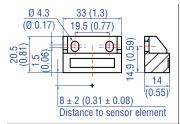
Ring magnet Part no. 402 316

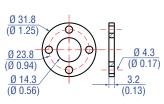
Material: PA ferrite coated Weight: Approx. 13 g Surface pressure: Max. 20 N/mm² Operating temperature: -40...+100 °C (-40...+212 °F)

Position magnet

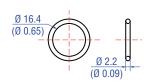
Magnet spacer

O-rings









Block magnet L Part no. 403 448

Material: Plastic carrier with hard ferrite magnet Weight: Approx. 20 g Fastening torque for M4 screws: 1 Nm Operating temperature: -40...+75 °C (-40...+167 °F)

This magnet may influence the sensor performance specifications for some applications

Magnet spacer Part no. 400 633

Material: Aluminum Weight: Approx. 5 g Surface pressure: Max. 20 N/mm² Fastening torque for M4 screws: 1 Nm

O-ring for threaded flange M18×1.5-6g Part no. 401 133

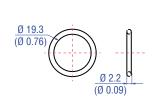
Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)

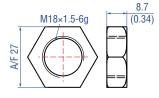
O-ring for threaded flange 34"-16 UNF-3A Part no. 560 315

Material: Fluoroelastomer Durometer: 75 ± 5 Shore A Operating temperature: -40...+204 °C (-40...+400 °F)

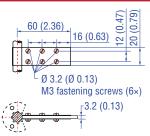
O-ring

Mounting accessories



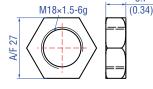






O-ring for threaded flange M22×1.5-6q Part no. 561 337

Material: FPM Durometer: 75 Shore A Operating temperature: -20...+200 °C (-6...+392 °F)



Hex jam nut M18×1.5-6g Part no. 500 018

Material: Steel, zinc plated

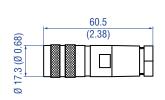
Hex jam nut 3/4"-16 UNF-3A Part no. 500 015

Material: Steel, zinc plated

Fixing clip Part no. 561 481

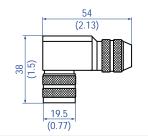
Application: Used to secure sensor rods (Ø 10 mm (Ø 0.39 in.)) when using an U-magnet or block magnet Material: Brass, non-magnetic

Cable connectors*



M16 female connector (6 pin), straight Part no. 370 423

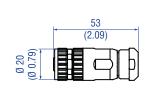
Material: Zinc nickel plated Termination: Solder Cable Ø: 6...8 mm (0.24...0.31 in.) Operating temperature: -40...+100 °C (-40...+212 °F) Ingress protection: IP65/IP67 (correctly fitted) Fastening torque: 0.6 Nm



M16 female connector (6 pin), angled

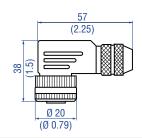
Part no. 370 460

Material: Zinc nickel plated
Termination: Solder
Cable Ø: 6...8 mm (0.24...0.31 in.)
Wire: 0.75 mm² (20 AWG)
Operating temperature:
-40...+95 °C (-40...+203 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.6 Nm



M12 A-coded female connector (4 pin/5 pin), straight Part no. 370 677

Material: GD-Zn, Ni
Termination: Screw
Contact insert: CuZn
Cable Ø: 4...8 mm (0.16...0.31 in.)
Wire: 1.5 mm²
Operating temperature:
-30...+85 °C (-22...+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.6 Nm



M12 A-coded female connector (5 pin), angled Part no. 370 678

Material: GD-Zn, Ni
Termination: Screw; max. 0.75 mm²
Contact insert: CuZn
Cable Ø: 5...8 mm (0.2...0.31 in.)
Wire: 0.75 mm² (18 AWG)
Operating temperature:
-25...+85 °C (-13...+185 °F)
Ingress protection: IP67 (correctly fitted)
Fastening torque: 0.4 Nm

Cables



PVC cable Part no. 530 032

Material: PVC jacket; gray Features: Twisted pair, shielded, flexible Cable Ø: 6 mm (0.23 in.) Cross section: $3 \times 2 \times 0.14$ mm² Bending radius: $10 \times D$ (fixed installation) Operating temperature: -40...+105 °C (-40...+221 °F)



PUR cable Part no. 530 052

Material: PUR jacket; orange Features: Twisted pair, shielded, highly flexible, halogen free, suitable for drag chains, mostly oil & flame resistant Cable Ø: 6.4 mm (0.25 in.) Cross section: $3 \times 2 \times 0.25 \text{ mm}^2$ Bending radius: $5 \times D$ (fixed installation) Operating temperature: -30...+80 °C (-22...+176 °F)



FEP cable Part no. 530 112

Material: FEP jacket; black Features: Twisted pair, shielded, flexible, high thermal resistance, mostly oil & acid resistant Cable Ø: 7.6 mm (0.3 in.) Cross section: $4 \times 2 \times 0.25$ mm² Bending radius: $8-10 \times D$ (fixed installation) Operating temperature: -100...+180 °C (-148...+356 °F)



FEP cable Part no. 530 157

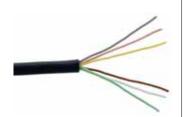
Material: FEP jacket; black Features: Twisted pair, shielded Cable \emptyset : 6.7 mm (0.26 in.) Cross section: $3 \times 2 \times 0.14$ mm² Operating temperature: -40...+180 °C (-40...+356 °F)

Color of connectors and cable jacket may change. Color codes for the individual wires and technical properties remain unchanged. Controlling design dimensions are in millimeters and measurements in () are in inches

^{*/} Follow the manufacturer's mounting instructions

Cable

Cable sets



Silicone cable Part no. 530 176

Material: Silicone jacket; black Features: Twisted pair, shielded Cable Ø: 6.3 mm (0.25 in.) Cross section: 3 × 2 × 0.14 mm² Bending radius: 7 × D (fixed installation)

Operating temperature: -50...+150 °C

(-58...+302 °F)



Cable with M12 A-coded female connector (5 pin), straight - pigtail Part no. 370 673

Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67 (correctly fitted) Operating temperature: -25...+80 °C (-13...+176 °F)



Cable with M12 A-coded female connector (5 pin), angled - pigtail Part no. 370 675

Material: PUR jacket; black Features: Shielded Cable length: 5 m (16.4 ft) Ingress protection: IP67 (correctly fitted) Operating temperature: -25...+80 °C (-13...+176 °F)

Programming tools







Hand programmer for analog output Part no. 253 124

Part no. 253 408

Easy teach-in-setups of stroke length and direction on desired zero / span positions. For sensors with 1 $\stackrel{\cdot}{\text{magnet}}$ Features snap-in mounting on standard DIN rail (35 mm). This programmer can be permanently mounted in a control cabinet and includes a program/run switch. For sensors with 1 magnet.

- Cabinet programmer for analog output TempoLink® kit for Temposonics® R-Series V
 - Part no. TL-1-0-AD60 (for D60) Part no. TL-1-0-AS00 (for cable outlet) Part no. TL-1-0-AD34 (for D34)
 - Connect wirelessly via Wi-Fi enabled device or via USB with the diagnostic
 - Simple connectivity to the sensor via 24 VDC power line (permissible cable length: 30 m)
 - · User friendly interface for mobile devices and desktop computers
 - See data sheet "TempoLink® smart assistant" (document part no.: 552070) for further information

Controlling design dimensions are in millimeters and measurements in () are in inches Color of connectors and cable jacket may change. Color codes for the individual wires and technical properties remain unchanged.

Extension cables M12



PVC cable with M12 female connector (6 pin), straight – pigtail

PVC cable (part no. 530 032) with M12 female connector, straight (part no. 370 677)

Order code:

K2-A-370677-xxxxyy-530032-0

(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



PUR cable with M12 female connector (6 pin), straight – pigtail

PUR cable (part no. 530 052) with M12 female connector, straight (part no. 370 677)

Order code:

K2-A-370677-xxxxyy-530052-0

(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



FEP cable with M12 female connector (6 pin), straight – pigtail

FEP cable (part no. 530 112) with M12 female connector, straight (part no. 370 677)

Order code:

K2-A-370677-xxxxyy-530112-0

(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")

Extension cables M16



PVC cable with M16 female connector (6 pin), straight – pigtail

PVC cable (part no. 530 032) with M16 female connector, straight (part no. 370 423)

Order code:

K2-A-370423-xxxxyy-530032-0

(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



PUR cable with M16 female connector (6 pin), straight – pigtail

PUR cable (part no. 530 052) with M16 female connector, straight (part no. 370 423)

Order code:

K2-A-370423-xxxxyy-530052-0

(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")



FEP cable with M16 female connector (6 pin), straight – pigtail

FEP cable (part no. 530 112) with M16 female connector, straight (part no. 370 423)

Order code:

K2-A-370423-xxxxyy-530112-0

(where xxxx = cable length and yy = unit in centimeters "CM" or feet "FT")

Notice for extension cables M12/M16

Standard cable lengths					
Meters	Feet	Code			
1.5	5	0150			
2	6.6	0200			
4.6	15	0460			
5	16.4	0500			
7.6	25	0760			
10	32.8	1000			
15.2	50	1520			

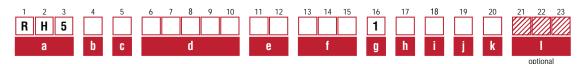
For additional extension cables reference the accessory catalog for industrial sensors (document part no.: <u>551444</u>).

Color of connectors and cable jacket may change. Color codes for the individual wires and technical properties remain unchanged.

Temposonics® R-Series ∨ RH5 Analog

Data Sheet

ORDER CODE



a Sensor model

R H 5 Rod

b Design

- **B** Base unit (only for replacement)
- J Threaded flange M22×1.5-6g (rod Ø 12.7 mm), stroke length: 25...5900 mm (1...232 in.)
- M Threaded flange M18×1.5-6g (standard)
- S Threaded flange ³/₄"-16 UNF-3A (standard)
- T Threaded flange 3/4"-16 UNF-3A (with raised-face)

c Mechanical options

- **A** Standard
- **B** Bushing on rod end (only for design »M«, »S« & »T«)
- M Thread M4 at rod end (only for design »M«, »S« & »T«)
- V Fluorelastomer seals for the sensor electronics housing

d Stroke length

X X X X M 0025...7620 mm

Standard stroke length (mm)	Ordering steps
25 500 mm	5 mm
500 750 mm	10 mm
7501000 mm	25 mm
10002500 mm	50 mm
25005000 mm	100 mm
50007620 mm	250 mm
X X X X U 001.0300.0	0 in.

Standard stroke length (in.)	Ordering steps	
1 20 in.	0.2 in.	
20 30 in.	0.4 in.	
30 40 in.	1.0 in.	
40100 in.	2.0 in.	
100200 in.	4.0 in.	
200 300 in	10 0 in	

Non-standard stroke lengths are available; must be encoded in 5 mm/0.1 in. increments.

e Number of magnets

0 X 01...02 Position(s) (1...2 magnet(s))

f | Connection type

Connector

- D 3 4 M12 male connector (5 pin)
- D 6 0 M16 male connector (6 pin)

Angled cable outlet

- E X XX m/ft. PVC cable (part no. 530 032)
 E01...E30 (1...30 m/3...99 ft.)
 See "Frequently ordered accessories" for cable specifications
- G X XX m/ft. FEP cable (part no. 530 157)
 G01...G30 (1...30 m/3...99 ft.)
 See "Frequently ordered accessories" for cable specifications
- L X XX m/ft. PUR cable (part no. 530 052)
 L01...L30 (1...30 m/3...99 ft.)
 (Note the temperature range of the cable!)
 See "Frequently ordered accessories" for cable specifications
- XX m/ft. Silicone cable (part no. 530 176)
 U01...U30 (1...30 m/3...99 ft.)
 See "Frequently ordered accessories" for cable specifications

Straight cable outlet

- H X X XX m/ft. PUR cable (part no. 530 052)
 H01...H30 (1...30 m/3...99 ft.)
 (Note the temperature range of the cable!)
 See "Frequently ordered accessories" for cable specifications
- R X X XX m/ft. PVC cable (part no. 530 032)

 R01...R30 (1...30 m/3...99 ft.)

 See "Frequently ordered accessories" for cable specifications
- T X X XX m/ft. FEP cable (part no. 530 112)
 T01...T30 (1...30 m/3...99 ft.)
 See "Frequently ordered accessories" for cable specifications

Encode in meters if using metric stroke length. Encode in feet if using US customary stroke length.

g System

1 Standard

h Output

A Current

V Voltage

i Function

- 1 Position (1 or 2 magnets/outputs)
- Position and speed (1 magnet and 2 outputs)

 Specify the maximum speed value in section
- Position and velocity (1 magnet and 2 outputs)

 Specify the maximum velocity value in section
- 4 Position and reverse position (1 magnet and 2 outputs)
- Position and temperature inside the sensor electronics housing (1 magnet and 2 outputs)
- 6 Differential (2 magnets and 1 output)

j Options

- **0** Standard
- 3 Over range output mode

k Output range

- **0** 0...10 VDC or 4...20 mA
- **1** 10...0 VDC or 20...4 mA
- **2** –10...+10 VDC or 0...20 mA
- **3** +10...-10 VDC or 20...0 mA
- V 0...10 VDC for position, -10...+10 VDC for velocity

I Max. speed or velocity value

(optional: use when ii "Function" is 2 or 3)

For metric stroke lengths encode speed or velocity in m/s for the values 0.01 to 9.99 m/s (001...999)

For US customary stroke lengths encode speed or velocity in inches/s for the values 1 to 400 in./s (001...400)

To get a speed or velocity output of 0.025 m/s or 10 m/s for the R-Series V Analog, enter code (00E) for 0.025 m/s or (A00) for 10.0 m/s in the order code.

NOTICE

- Specify the number of magnets for your application and order the magnets separately.
- The number of magnets is limited by the stroke length.
 The minimum allowed distance between magnets (i.e. front face of one to the front face of the next one) is 75 mm (3 in.).
- Use magnets of the same type for differential/multi-position measurement.

DELIVERY



RH5-B:

- Base unit (without flange & rod assembly)
- 3 × socket screws M4×59

RH5-J/-M/-S/-T:

- Sensor
- 0-ring

Accessories have to be ordered separately.

Manuals, Software & 3D Models available at: www.temposonics.com

Temposonics® R-Series ∨ RH5 Analog

Data Sheet

GLOSSARY

A

Analog output

For a sensor with analog output, the measured value is output as an analog voltage signal or current signal.

n

Differential

For differential measurement, the distance between the two position magnets is output as a value.

(→ multi-position measurement)

M

Max. speed or velocity value

For speed or velocity, the output value generated is scaled based on the maximum speed or velocity value indicated in the order code.

Measuring direction

- Forward: Values increasing from sensor electronics housing to rod end/profile end
- Reverse: Values decreasing from sensor electronics housing to rod end/profile end

Multi-position measurement

During the measurement cycle, the positions of every magnet on the sensor are simultaneously reported. The velocity or speed is continuously calculated based on these changing position values as the magnets are moved.

0

Over range output mode

When enabled this mode allows the position output values to continue to increase or decrease when the magnet travels beyond the active stroke range.

R

Resolution

The sensor precisely measures time to provide the position measurement. For the analog output the measured time value is converted into an analog voltage signal or current signal using a high-performance **D**igital to **A**nalog **C**onverter (DAC) having 16 bits of resolution.

S

Speed

The output value for speed indicates how fast the position magnet is being moved, independent of the measuring direction. (\rightarrow Velocity)

T

Temperature inside the sensor electronics housing

The temperature inside the sensor electronics housing is reported as an analog voltage signal or current signal. For each output range, the 0 % output value has the factory default setpoint at -40 °C, and the 100 % output value has the default setpoint at +100 °C.

Note: A dedicated temperature chip is used for the output signal and its values may vary from those reported on the TempoLink® application screen.

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Velocity

The output value for velocity indicates how fast the position magnet is being moved, and in which direction. (\rightarrow Speed)



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552061 Rev C (EN) 08/2023

UK CERTIFIED



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