



Temposonics

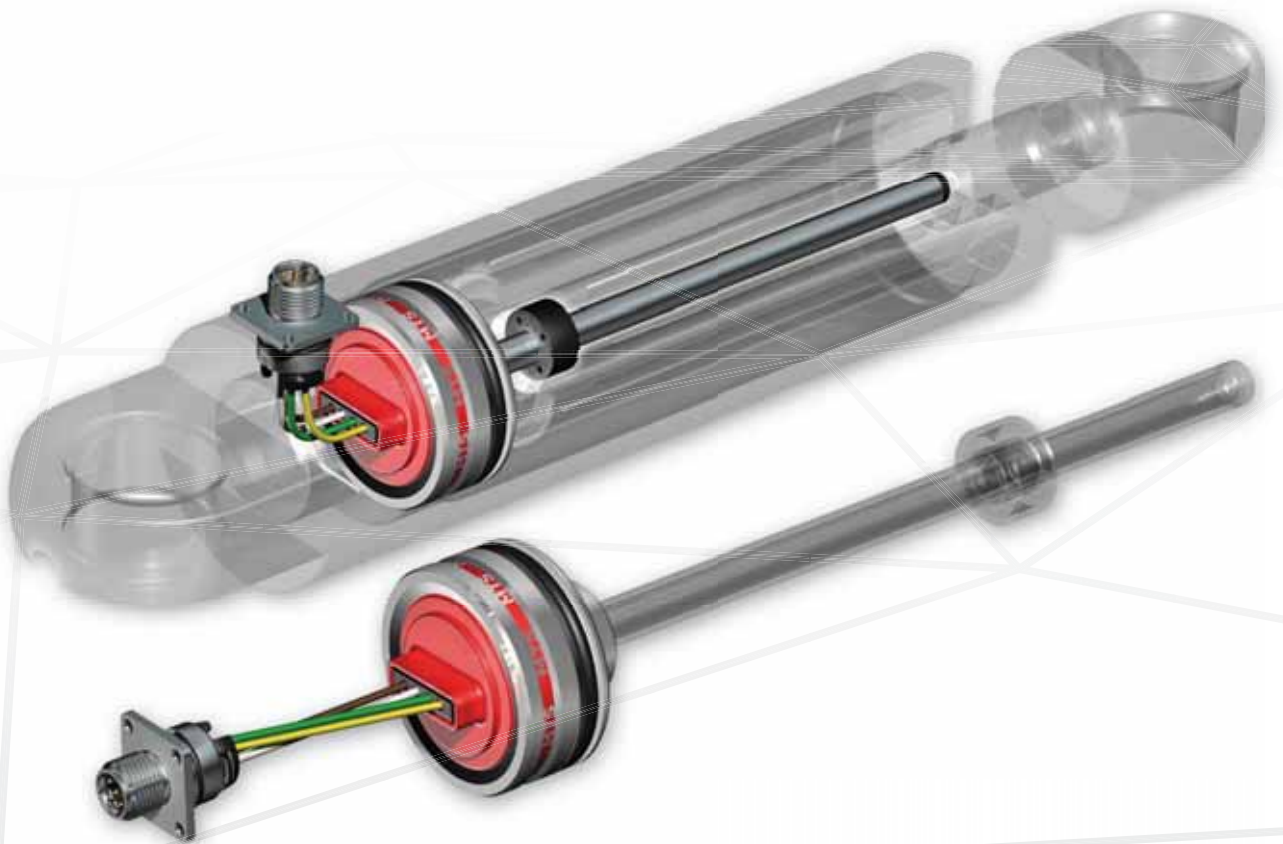
AN AMPHENOL COMPANY

Data Sheet

MH-Series MH200

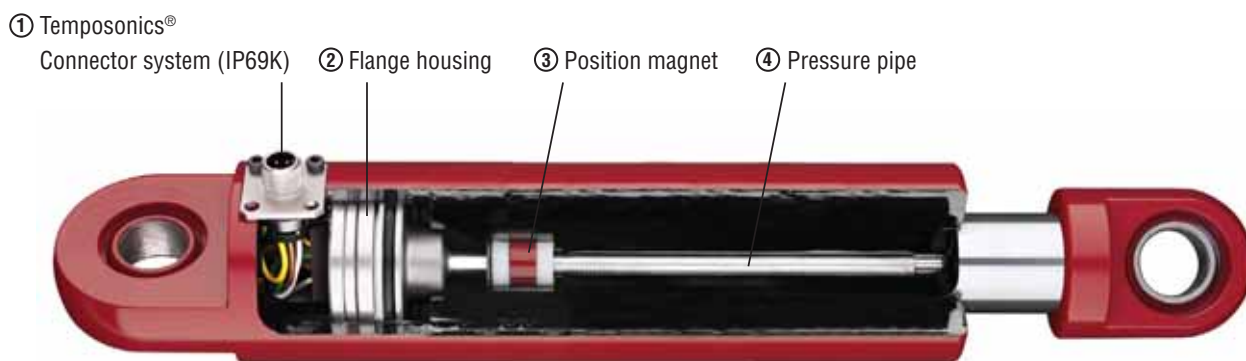
Magnetostrictive Linear Position Sensors

- Stroke range up to 5000 mm
- Linearity < 0.04 % F.S.
- Resolution typ. 0.5 mm



1. Product description and technology

Temposonics® sensors can be used in versatile mobile machines without any restriction and replace contact-based linear sensors like potentiometers. Highly dynamic systems are controlled safely by means of Temposonics® sensors, thus enhancing the productivity, availability and quality of the working process of the machine. Insensitive to vibration, shocks, dust and weathering influence and electro-magnetic disturbances. Temposonics® MH Series sensors are successfully used in front axle and articulated frame steering cylinders, hydraulic jacks and in steering systems for hydraulic units on agricultural and construction machinery.



Simple Mechanics

The extremely robust sensor consists of the following main parts:

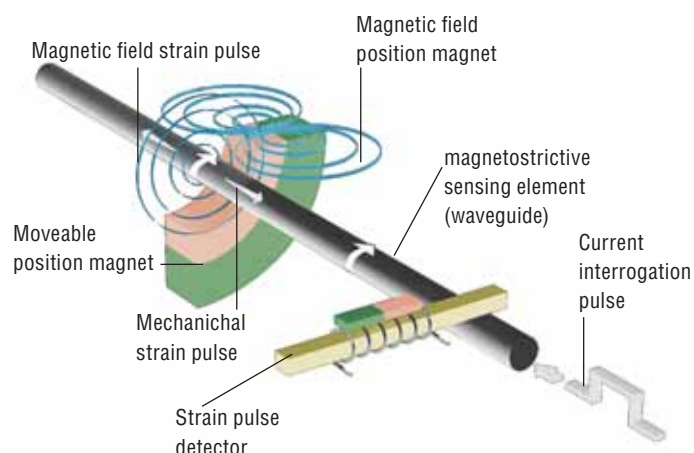
- ① The innovative connector system which is easy to install in a few seconds, any soldering or crimping needless, dust-and waterproof up to IP69K.
- ② The flange housing with built-in electronics and signal converter.
- ③ The position magnet as only moving part, which is assembled into the piston bottom. This permanent magnet travels wear-free and contactless along the pressure pipe and measures the actual position.
- ④ The pressure pipe placed within the drilled piston rod contains the protected magnetostrictive sensing element.

- Due to small dimensions MH sensors require only little space
- Suitable for operating pressures up to 320 bar
- Unaffected by surrounding media such as ageing or foaming oil
- Insensitive to shock and vibration
- Designed for all current supply voltages (12/24 VDC)
- Temposonics® sensors offer all common used output signals:
 - Analog: VDC/mA
 - Bus protocols: CANopen, SAE J1939

Magnetostriction

Temposonics® linear sensors are based on the magnetostrictive technology. By measuring the actual position with a non-contact position magnet the sensor operates 100% wear-free. The absolute operating principle enables reliable readings without any reference point or recalibration. A mechanical strain pulse is triggered by the travelling position magnet. The runtime of this ultrasonic wave is measured precisely and compiled into standard electronic output signals.

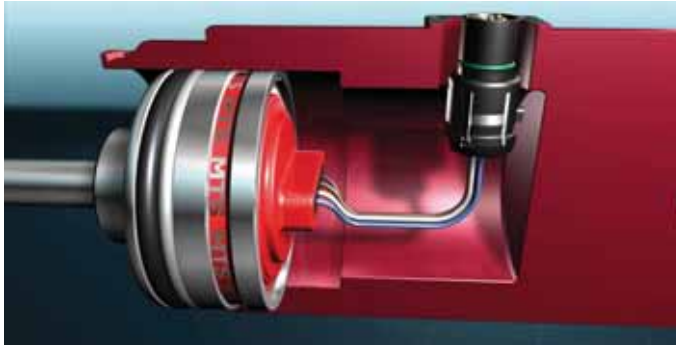
Measurement principle



2. Temposonics® connector system M12

MTS presents the innovative connector system for Temposonics® MH-Series

The Temposonics® Connector System meets the highest protection requirements important for a harsh environment in mobile hydraulic applications. Protection type IP69K performs water and dust proof. In addition it is even resistive against high pressure water cleaning.



- ❶ The MH sensor is delivered by Temposonics together with the new connector system:
The connector insert carrier is already connected to the sensor conductors, i.e. no soldering, any colour or connection mistake.



- ❷ The connector insert is taken out of the cylinder through a bore hole. The flange can easily be clicked in position from outside.



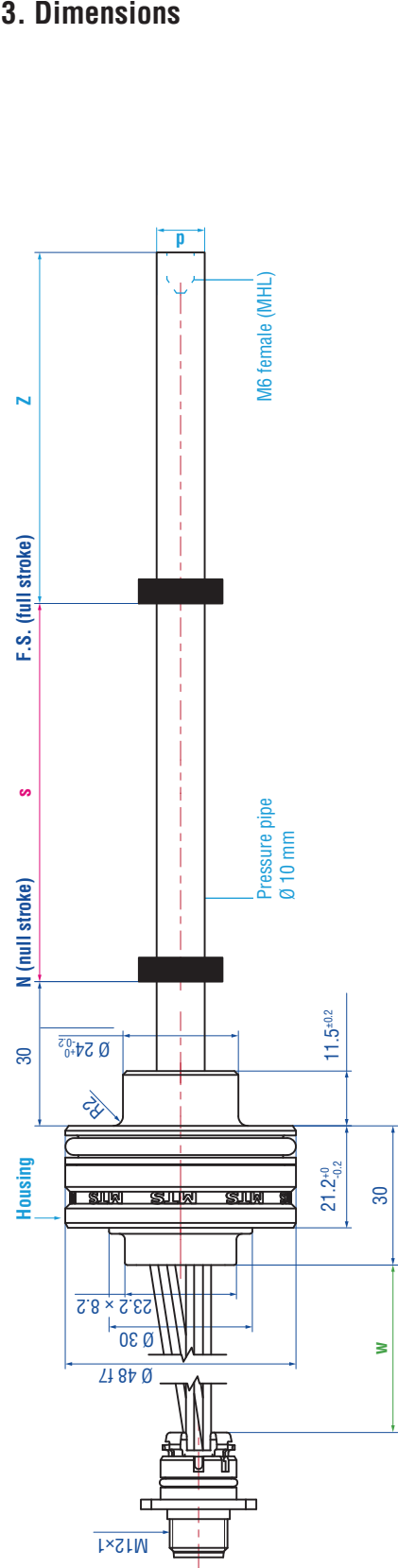
- ❸ Four standard screws must be tightened to mount the connector system on the cylinder. In case of using angled type connectors the connector insert can be rotated inside the flange in 45° steps.



- ❹ With a corresponding mating plug the connector system fulfills an IP rating of IP69K.

- Absolutely easy and safe installation.
- No brazing or crimping of connecting leads is required.

3. Dimensions

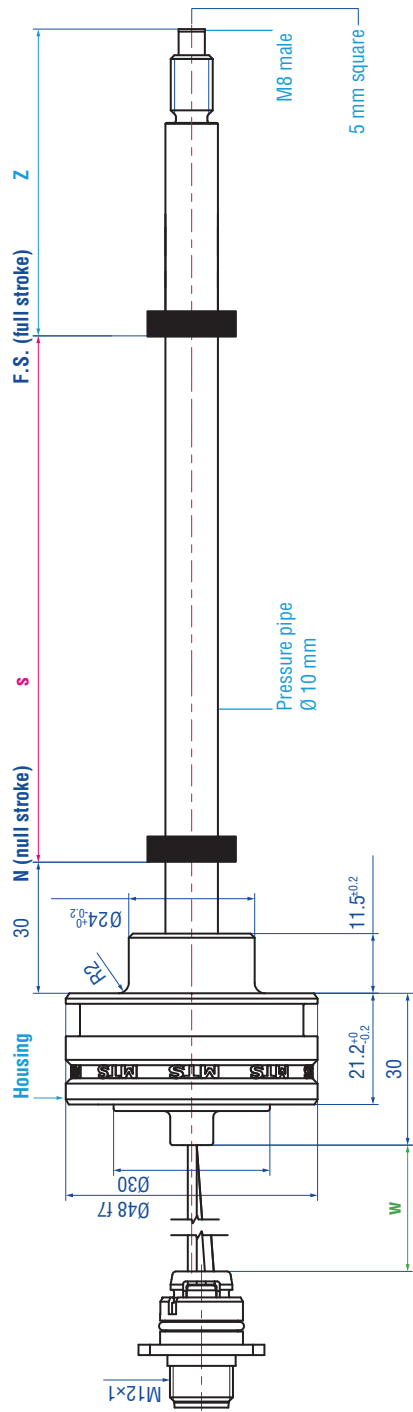


Mechanical configurations		Model no.	MH	C	1	5	0	0	M	N	1	2	G	-	3	-	V02	A01	C01	J01	4	7F	3	FD
Form factor	C	Z = 63.5 mm (s < 5000 mm), Ø 10 mm pressure pipe																						
	L	Z = 69.5 mm (s < 5000 mm), Ø 10 mm pressure pipe																						
Stroke range	s	2520...5000 mm (in 20 mm steps)																						
Wire length	w	60...240 mm (in 20 mm steps)																						

Electrical configurations		Model no.	MH	C	1	5	0	0	M	N	1	2	G	-	3	-	V02	A01	C01	J01	4	7F	3	FD
MH Analog	G	1 = VDC 3 = GND 4 = Sig 2 = n.c.																						
	H	1 = VDC 2 = Sig 3 = GND 4 = n.c.																						
MH Digital	F	2 = VDC 3 = GND 4 = CAN HI 5 = CAN LO 1 = n.c.																						
	A01	4...20 mA																						
MH Analog	V02	0.5...9.5 VDC																						
	C01	CANopen																						
MH Digital	J01	SAE J1939																						
	3	250 kbit/sec																						
Baudrate	4	125 kbit/sec																						
	7F	hex																						
Node ID	FD	hex																						

All dimensions in mm

Please see detailed model configuration on page 13 and 15.
 Please see document 551308 for MH with cable version.



Mechanical configurations

Form factor	Q	Z = 85.5 mm (s < 5000 mm), Ø 10 mm pressure pipe
Stroke range	s	2520...5000 mm (in 20 mm steps)
Wire length	w	60...240 mm (in 20 mm steps)

Model no. MH **Q** - **1 5 0 0** **M - N** **1 2 G** - **3** - **V02** **A01**
e.g.: s = 1500 mm
e.g.: w = 120 mm

Electrical configurations

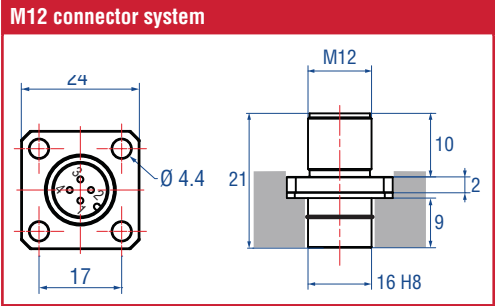
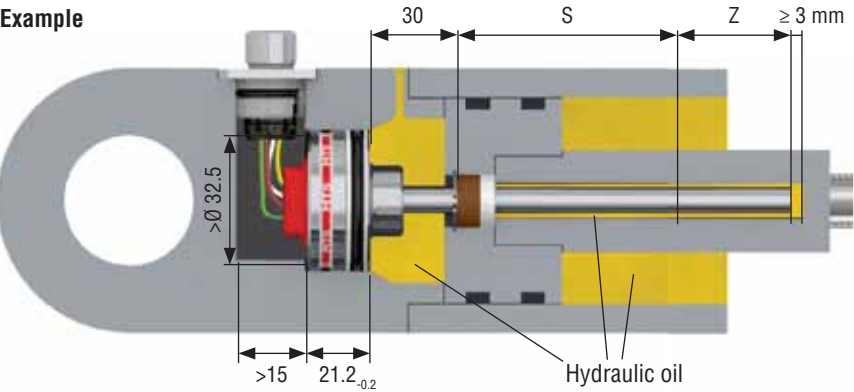
MH Analog	G	1 = VDC 3 = GND 2 = Sig 4 = n.c.
	H	1 = VDC 3 = GND 2 = Sig 4 = n.c.
MH Digital	F	2 = VDC 3 = GND 4 = CAN HI 5 = CAN LO 1 = n.c.
MH Analog	A01	4...20 mA
	V02	0.5...9.5 VDC
MH Digital	C01	CANopen
	J01	SAE J1939
Baudrate	3	250 kbit/sec
	4	125 kbit/sec
Node ID	7F	hex
	FD	hex

4. In Cylinder assembly

Mechanical installation

The robust Temposonics® model MH sensor is designed for direct stroke measurement in hydraulic cylinders.
 The Temposonics® MH sensor can be installed from the head side or the rod side of the cylinder depending on the cylinder design.

Example

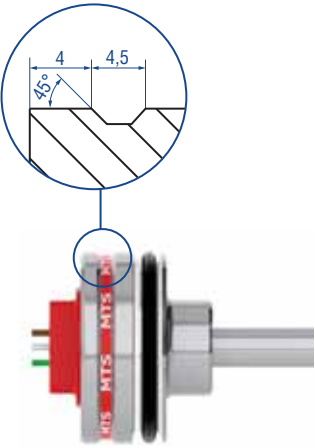


Sensor installation

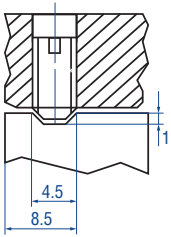
The method of installation is entirely dependent on the cylinder design.
 While the most common method of installation is from the rod side of the cylinder, an installation from the head side of the cylinder is also possible. In both installation methods, the hermetic sealing of the cylinder is given by an O-ring with additional back up ring.

Please pay attention:

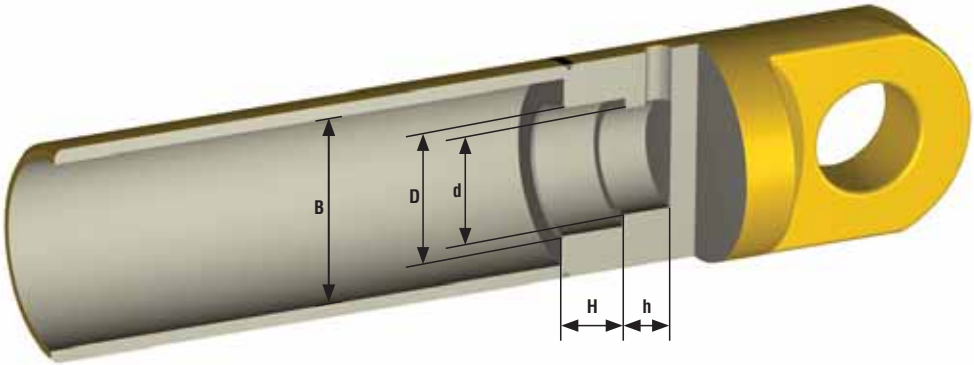
- The position magnet shall not touch the pressure pipe.
- Do not exceed operating pressure.
- Piston rod drilling:
 Depth: $S + Z + 3 \text{ mm}$
 Diameter: $\varnothing 13 \text{ mm}$ minimum



Flange housing
 with O-ring and
 back-up ring



Example:
 e.g. retaining with set screw
 DIN 913 M5 × 10 (with flat point!)
 max. torque 0.5 Nm



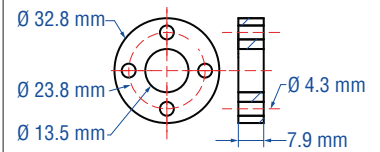
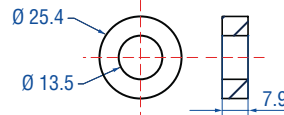
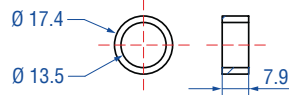
Type	B Ø Cylinder	D Ø min.	H Depth	d Ø min.	h Depth
MH	≥ 52	48H8 screwed 48G7 welded	≥ 21.2	≥ 32.5 ≤ 40	≥ 15

Please pay attention to installation manual!

All dimensions in mm

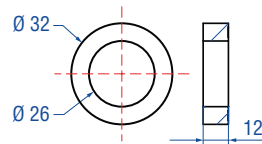
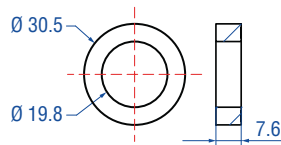
4.1 Position magnets

Position magnets (please order separately) **for installation without support tube**



Part no.	401 032	400 533	201 542-2
Dimensions			
OD _M	17.4 mm	25.4 mm	32.8 mm
ID _M	13.5 mm	13.5 mm	13.5 mm
Height	7.9 mm	7.9 mm	7.9 mm
Characteristics			
Material	PA neobond	PA ferrite	PA ferrite
Weight	ca. 5 g	ca. 10 g	ca. 14 g
Operating temperature	-40...+100 °C	-40...+100 °C	-40...+100 °C
Surface pressure*	max. 20 N/mm ²	max. 40 N/mm ²	max. 40 N/mm ²
Fastening torque for M4 screws	-	-	max. 1 Nm

Position magnets (please order separately) **for installation with support tube**

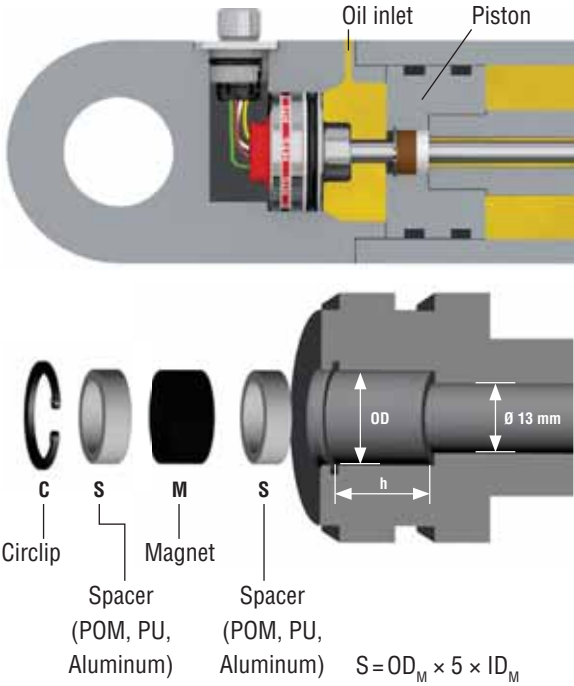


Part no.	402 316	403 974
Dimensions		
OD _M	30.5 mm	32.0 mm
ID _M	19.8 mm	26.0 mm
Height	7.6 mm	12.0 mm
Support tube		
	18 × 1.5 mm	22 × 2 mm
Characteristics		
Material	PA ferrite coated	NdFeB
Weight	ca. 13 g	ca. 20 g
Operating temperature	-40...+100 °C	-40...+100 °C
Surface pressure*	20 N/mm ²	20 N/mm ²

*max. mechanical burden, e.g.
by circlip, lock washers etc.

4.2 Position magnet (M) and magnet assembly with spacer (S) in piston

4.2.1 Installation without support tube

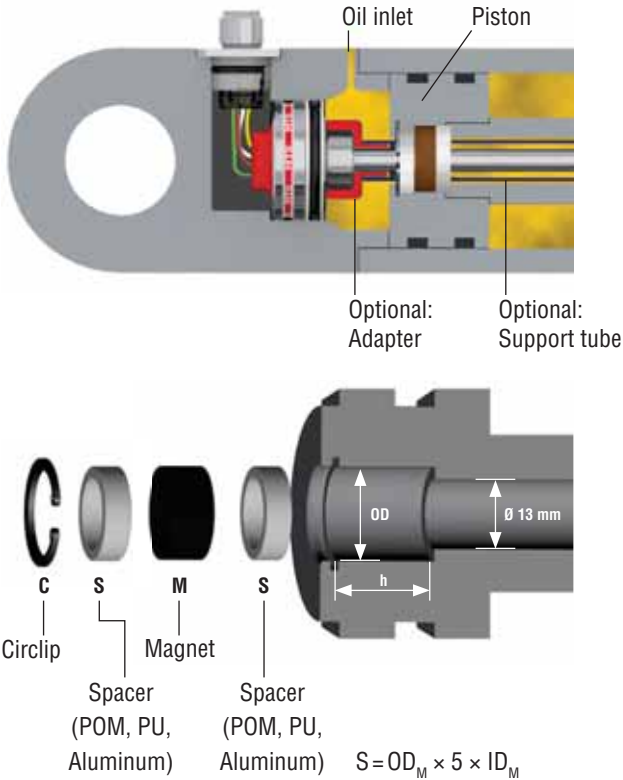


Magnet (M)	401 032	400 533	201 542-2
OD	17.5 mm ^{+0.2}	25.5 mm ^{+0.2}	32.9 mm ^{+0.2}
h - Depth	13.5 mm	13.5 mm	13.5 mm

NOTICE

Spacers, washers, pretension parts etc. are not part of the shipment!

4.2.2 Installation with support tube



Stroke range	Support tube	Piston rod drilling	Magnet
2640...3240 mm	Ø 18 x 1.5 mm	Ø 22	402 316
3260...5000 mm	Ø 22 x 2.0 mm	Ø 26	403 974

Magnet (M)	402 316	403 974
OD	30.6 mm ^{+0.2}	32.1 mm ^{+0.2}
h - Depth	13.5 mm	13.5 mm

NOTICE

Spacers, washers, pretension parts etc. are not part of the shipment!

NOTICE

For correct sensor installation and technical support please contact our application team

4.3 Support tube assembly for MH model MHQ



Please note that the support tube assembly and the adapter accessories is a proposal by Temposonics.

For further design information please consult Temposonics application engineering who will consult and clarify as required.

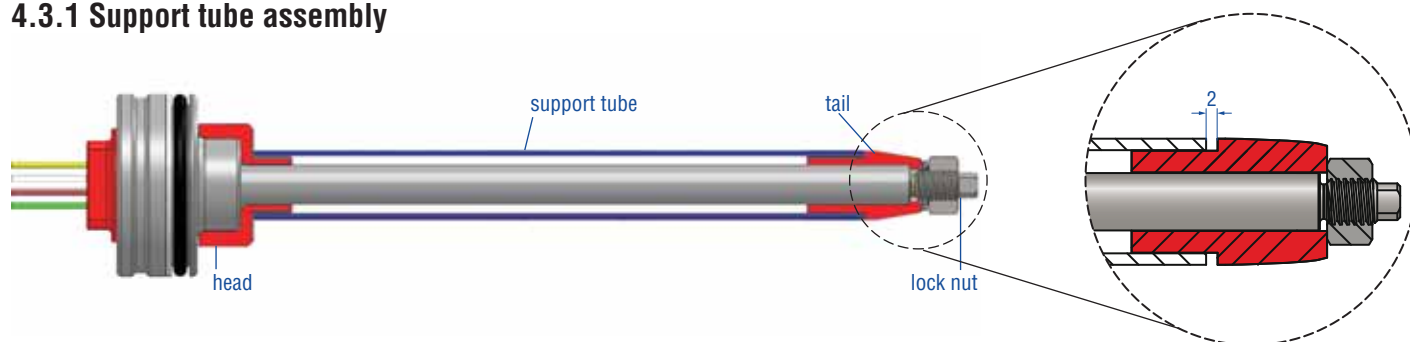
Please pay attention to:

- Support tube adapters must enable oilflow to get rid of air when cylinder gets oil filled
- Support tubes material is stainless steel 1.4301 (AISI 304) or 1.4305 (AISI 303).
If machining is conducted on stainless steel support tubes please make sure it does not induce magnetic properties to the material.
- Nut M8 to tighten with max. 4 Nm. Use glue to fix the nut
- Use a wrench 5 mm to hold the pressure pipe end when tighten the nut M8
- No torsional stress to apply on the pressure pipe
- Adapters material: stainless steel, aluminum, PA or POM
- Head and tail adapter: OD tolerances are applied in conjunction with the tolerances valid for the wall thickness of selected support tube



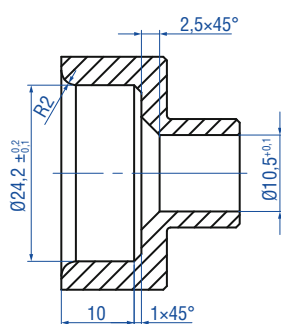
Adapters, support tube, locknuts, etc. are not part of the shipment.

4.3.1 Support tube assembly

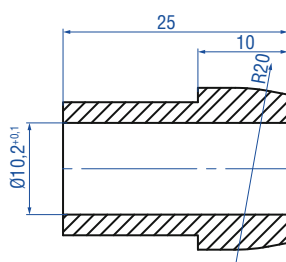


4.3.3 Assembly adapters

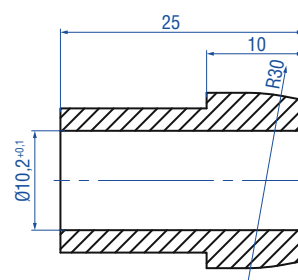
Head



Tail (for 18 × 1.5 mm support tube)



Tail (for 22 × 2 mm support tube)



NOTICE

For correct sensor installation and technical support please contact our application team

4.4 Operating conditions and load limits considering a sensor installation with support tube.

4.4.1 Vibration Ratings on Machines

Vibration ratings for machines are shown in the EU directive 2002/44/EC.

Real effective accelerations and forces within the hydraulic cylinder may exceed this level.

For the cylinder installation requiring a support tube an applied load collective has been defined in order to approve the design for the resonance frequency range.

Considering the results out of the load collective the operating grade for pressure and vibration loads has been conducted. The calculation follows the guideline published from Mechanical Engineering Research Community FKM Germany.

For pressurized hydraulic cylinders the operating grade is given wide below 100%.

Diagramm (operating grade in %)

100 % = Burst Level

50 % = 5.3 g Peak Acceleration

25 % = 1.5 g Effective Load Cycle, 2.15 g Peak Acceleration

0 % = without Load



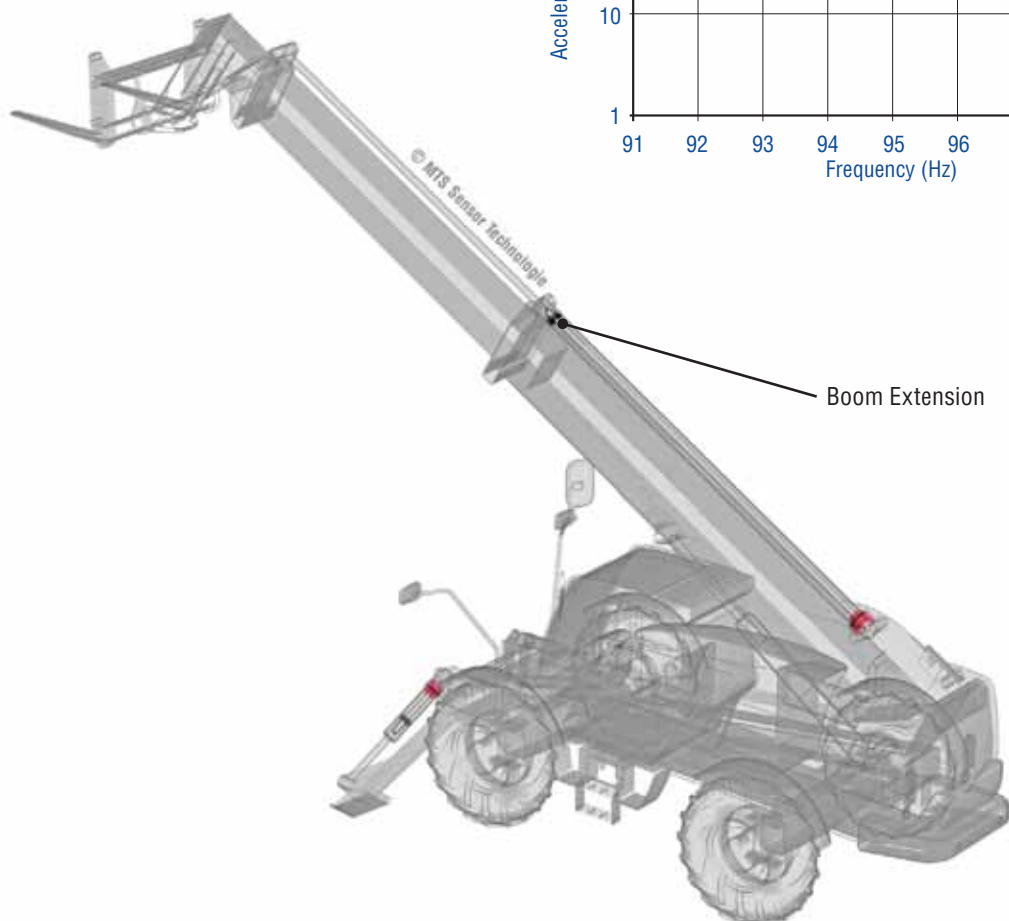
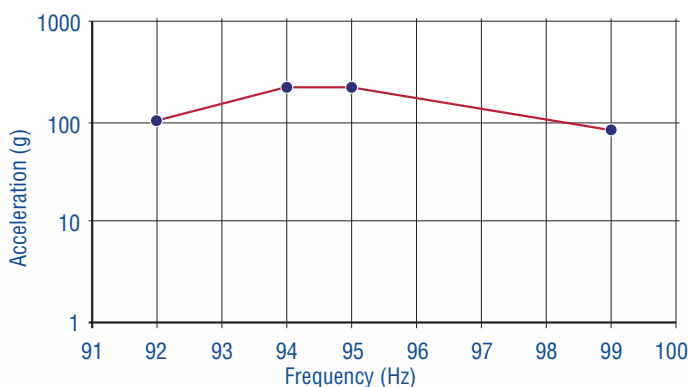
4.4.2 Load Cycle Test with Support Tube 22x2mm

Reference Cylinder- horizontal Installation.

Resonance Endurance Test 2.5×10^6 Load Cycles with Sinus Wave Form.

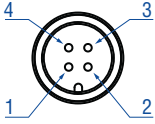
To perform and approve the mechanical load within the resonance range (94 Hz to 95 Hz). The test was passed without any permanent damages observed after this test.

Resonance Endurance Test



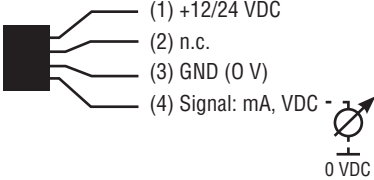
5. Electrical installation

MH Analog
PIN assignment M12 (4 pin)



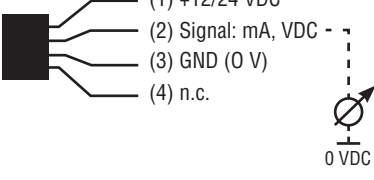
Pin	G	H
1	VDC	VDC
2	n.c.	Signal
3	GND	GND
4	Signal	n.c.

Pin assignment "G"



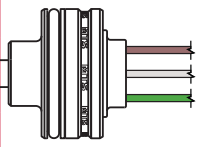
(1) +12/24 VDC
(2) n.c.
(3) GND (0 V)
(4) Signal: mA, VDC

Pin assignment "H"



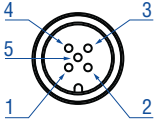
(1) +12/24 VDC
(2) Signal: mA, VDC
(3) GND (0 V)
(4) n.c.

MH Analog
wire assignment



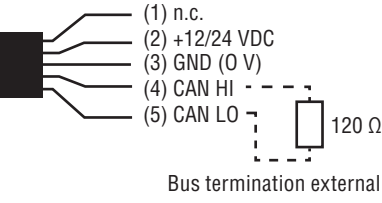
Color	Signal
BN	VDC
WH	GND
GN	Signal

MH Digital
PIN assignment M12 (5 pin)



Pin	F
1	n.c.
2	VDC
3	GND
4	CAN HI
5	CAN LO

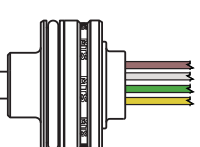
Pin assignment "F"



(1) n.c.
(2) +12/24 VDC
(3) GND (0 V)
(4) CAN HI
(5) CAN LO

120 Ω
Bus termination external

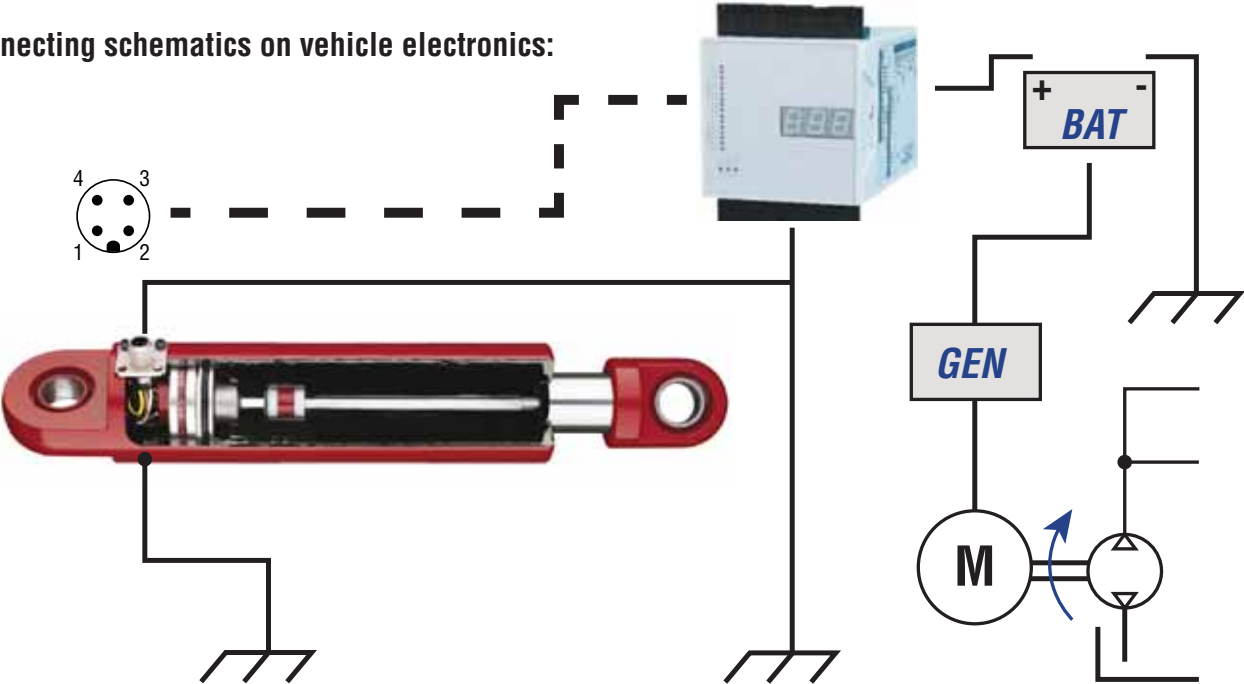
MH Digital
wire assignment



Color	Signal
BN	VDC
WH	GND
GN	CAN LO
YE	CAN HI

 Please pay attention to installation manual!

Connecting schematics on vehicle electronics:



All dimensions in mm

6. MH Analog: Technical data

Input		
Measured value	Position	
Stroke range	2520...5000 mm (in 20 mm steps)	
Output		
Signal characteristic	Analog output restricted by noise or A/D converter of control unit	
Voltage	0.5...9.5 VDC	
Current	4...20 mA	
Resolution	2520...3500 mm ≤ 0.5 mm	3520...5000 mm ≤ 1.0 mm
Power up time	Typ. 250 ms	
Mounting zone	30 mm	
Damping	63.5 mm 69.5 mm (M6 female) / 85.5 mm (M8 male)	
Accuracy		
Linearity	2520...3500 mm ≤ ±1.0 mm	
	3520...5000 mm ≤ ±2.0 mm	
Hysteresis	2520...3500 mm ≤ ±0.5 mm	
	3520...5000 mm ≤ ±1.0 mm	
Internal sample rate	2 ms	
Setpoint tolerance	≤ 2 mm	
Operating conditions		
Mounting position	Any	
Operating temperature electronics	−40...+105 °C	
Storage temperature	−25...+ 65 °C	
Fluid temperature	−30...+ 85 °C	
Dew point, humidity	EN60068-2-30, 90 % rel. humidity, no condensation	
Pressure	Without considering support tube assembly	
Operating pressure ratings	Pressure impulse test according DIN EN ISO 19879	
Nominal operating pressure (P _N)	320 bar	
Max. overload pressure in cylinder (P _{MAX})	400 bar	
Max. static proof pressure in cylinder (P _{PROOF})	550 bar	
IP rating		
M12 connector	EN60529 (IP69K) when plugged	
Sensor housing	EN60529 (IP67)	
Environmental testing		
Shock test	IEC 60068-2-27, 50 g (11 ms) single shock, 15 g (11 ms) at 1000 shocks per axis	
Vibration test	IEC 60068-2-64, 5 g (r.m.s.) Ø 10 mm pressure pipe (10...2000 Hz) – resonance frequencies excluded	
EMC	ISO 14982 Agricultural and forest machines	
test & evaluation	EN 13309 Construction machines	
	Immunity: ISO 11452-2 (200 V/m Antenna), ISO 11452-4 (200 mA BCI)	
	Emissions: CISPR 25	
	Transiente Impulses: ISO 7637-2	
	E.S.D.: ISO/TR 10605	
Materials and dimensions		
Pressure pipe (Ø 10 mm)	Stainless steel 1.4306 / AISI 304L	
Housing	Stainless steel 1.4305 / AISI 303	
Sealing	O-ring 40.87 × 3.53 mm NBR 80, back-up ring 42.6 × 48 × 1.4 PTFE	
M12 connector insert	Material: polyamide reinforces; O-ring 7 × 1.35 mm NBR 70; pins: brass with gold plated pins	
M12 flange	Brass nickel-plated with O-ring 13 × 1.6 NBR 70	
Electrical installation		
Connector	M12 male plug or cable assembly	
Supply voltage	12 VDC (tolerance range 8...32 VDC)	24 VDC (tolerance range 8...32 VDC)
Current consumption	Typ. ≤ 100 mA	Typ. ≤ 50 mA
Load (output VDC)	R _L ≥ 10 kΩ	R _L ≥ 10 kΩ
Load current (output VDC)	Typ. 1 mA	Typ. 1 mA
Loud (output mA)	R _L ≤ 250 Ω	R _L ≤ 500 Ω
Inrush current	Max. 2.5 A/2 ms	Max. 4.5 A/2 ms
Supply voltage ripple	< 1 % p-p	
Power drain	< 1 W	
Over voltage protection (GND-VDC)	Up to +36 VDC	
Polarity protection (GND-VDC)	Up to −36 VDC	
Insulation Resistance	R ≥ 10 MΩ @ 60 sec	
Electric strength	500 VDC (DC GND to chassis GND)	

6.1 Model configurator

M

H

a

b

M

c

d

3

e

f

a

Sensor model

M

H

Flange housing Ø 48 mm

b

Form factor

C

Pressure pipe Ø 10 mm, Damping: 63.5 mm

L

Pressure pipe Ø 10 mm, Damping: 69.5 mm, M6 female

Q

Pressure pipe Ø 10 mm, Damping: 85.5 mm, M8 male port

c

Stroke range (mm)

2520...5000 mm (in 20 mm steps)

d

Electrical wiring

M12 connector (VDC – GND – SIGN) incl. M12 flange

N

G

4 pin (1-3-4), 60...240 mm cable length (in 20 mm steps)

N

H

4 pin (1-3-2), 60...240 mm cable length (in 20 mm steps)

Cable assembly

T

A

300...9000 mm cable length (in 100 mm steps)

e

Supply voltage

3

+12/24 VDC

f

Output

V

0

2

0.5...9.5 VDC

A

0

1

4...20 mA

Examples cable length

N08G = 080 mm

N10H = 100 mm

Example cable length

T10A = 1000 mm

Scope of delivery:
Position sensor, O-ring, backup-ring and M12 connector system

Please order accessories separately!

Adapters, support tube, locknuts, spacers etc. are not part of Temposonics shipment. Please consult Temposonics for engineering support

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7. MH Digital: Technical data

Input		
Measured value	Position and velocity	
Stroke range	2520...5000 mm (in 20 mm steps)	
Velocity range	0...1000 mm/s	
Output		
Signal characteristic	Bus-protocol: SAE J1939, CANopen protocol according to CiA DS-301 V4.1, device profile DS-406 V3.1	
Resolution (position)	0.5 mm	
Resolution (velocity)	1 mm/s	
Boot up time	Typ. 400 ms	
Cycle time	CANopen: 2 ms	
	SAE J1939: 20 ms	
Mounting zone	30 mm	
Damping	63.5 mm	
	69.5 mm (M6 female) / 85.5 mm (M8 male)	
Accuracy		
Linearity	2520...3500 mm ≤ ±1.0 mm	
	3520...5000 mm ≤ ±2.0 mm	
Hysteresis	±0.5 mm	
Internal sample rate	2 ms	
Setpoint tolerance	±0.2 mm	
Operating conditions		
Mounting position	Any	
Operating temperature electronics	−40...+105 °C, Option: −40...+85 °C	
Storage temperature	−25...+ 65 °C	
Fluid temperature	−30...+ 85 °C	
Dew point, humidity	EN60068-2-30, 90 % rel. humidity, no condensation	
Pressure	Without considering support tube assembly	
Operating pressure ratings	Pressure impulse test according to DIN EN ISO 19879	
Nominal operating pressure (P _N)	320 bar	
Max. overload pressure in cylinder (P _{MAX})	400 bar	
Max. static proof pressure in cylinder (P _{PROOF})	550 bar	
IP rating		
M12 connector	EN60529 (IP69K) when plugged	
Sensor housing	EN60529 (IP67)	
Environmental testing		
Shock test	IEC 60068-2-27, 50 g (11 ms) single shock, 15 g (11 ms) at 1000 shocks per axis	
Vibration test	IEC 60068-2-64, 5 g (r.m.s.) Ø 10 mm pressure pipe (10...2000 Hz) – resonance frequencies excluded	
EMC test	ISO 14982 Agricultural and forest machines	
test & evaluation	EN 13309 Construction machines	
	Immunity: ISO 11452-2 (200 V/m Antenna), ISO 11452-4 (200 mA BCI)	
	Emissions: CISPR 25	
	Transiente Impulses: ISO 7637-2	
	E.S.D.: ISO/TR 10605	
Materials and dimensions		
Pressure pipe (Ø 10 mm)	Stainless steel 1.4306 / AISI 304L	
Housing	Stainless steel 1.4305 / AISI 303	
Sealing	O-ring: 40.87 × 3.53 mm NBR 80; back-up ring: 42.6 × 48 × 1.4 PTFE	
M12 connector insert	Material: polyamide reinforces; O-ring 7 × 1.35 mm NBR 70; pins: brass with gold plated pins	
M12 flange	Brass nickel-plated with O-ring 13 × 1.6 NBR 70	
Electrical installation		
Connector	M12 male plug or cable assembly	
Supply voltage	12 VDC (8...32 VDC)	24 VDC (8...32 VDC)
Current consumption	Typ. ≤ 100 mA	Typ. ≤ 50 mA
Inrush current	Max. 1.0 A @ 2 ms	Max. 1.5 A @ 2 ms
Bus termination (HI-LO)	120 Ω	
Supply voltage ripple	< 1 % p-p	
Power drain	< 1.5 W	
Over voltage protection (GND-VDC)	Up to +36 VDC	
Polarity protection (GND-VDC)	Up to −36 VDC	
Insulation Resistance	R ≥ 10 MΩ @ 60 sec.	
Electric strength	500 VDC (DC GND to chassis GND)	

7.1 Model configurator

	M	H						M					3						
	a	b	c						d	e	f			g	h		i		
a	Sensor model																		
M	H	Flange housing Ø 48 mm																	
b	Form factor																		
C	Pressure pipe Ø 10 mm, Damping: 63.5 mm																		
L	Pressure pipe Ø 10 mm, Damping: 69.5 mm, M6 female																		
Q	Pressure pipe Ø 10 mm, Damping: 85.5 mm, M8 male																		
c	Stroke range (mm)																		
				2520...5000 mm (in 20 mm steps)															
d	Electrical wiring																		
M12 connector incl. M12 flange																			
N			F	5 pin (2-3-4-5), 60...240 mm cable length (in 20 mm steps)															
Cable assembly																			
T			A	300...9000 mm cable length (in 100 mm steps)															
e	Supply voltage																		
3	+12/24 VDC																		
f	Output																		
C	0	1	CANopen cycle time 1 ms (default setting)																
J	0	1	SAE J1939 cycle time 20 ms (default setting)																
g	Baud rate																		
CANopen (C01)																			
0	1000 kbit/s																		
1	800 kbit/s																		
2	500 kbit/s																		
3	250 kbit/s																		
4	125 kbit/s																		
6	50 kbit/s																		
SAE J1939 (J01)																			
3	250 kbit/s																		
h	Node-ID (CANopen) / Source adress (SAE J1939)																		
CANopen (C01)																			
			hex 01...7F																
SAE J1939 (J01)																			
			hex 01...FD																
i	Operating temperature																		
L	-40...+85 °C																		

Examples cable length

N08F = 080 mm

Example cable length

T10A = 1000 mm

Scope of delivery:

Position sensor, O-ring, backup-ring and M12 connector system

Please order accessories separately!

Adapters, support tube, locknuts, etc. are not part of Temposonics shipment. Please consult Temposonics for engineering support

Accessories

Position magnets for installation without support tube

		
OD17.4 Ring magnet Part no. 401 032	OD25.4 Ring magnet Part no. 400 533	OD33 Ring magnet Part no. 201 542-2
Material: PA-Neobind Weight: ca. 5 g Operating temperature: -40...+100 °C Surface pressure: max. 20 N/mm ²	Material: PA-Ferrit Weight: ca. 10 g Operating temperature: -40...+100 °C Surface pressure: max. 40 N/mm ²	Material: PA-Ferrit-GF20 Weight: ca. 14 g Operating temperature: -40...+100 °C Surface pressure: max. 40 N/mm ² Fastening torque for M4 screw: max. 1 Nm

Position magnets for installation with support tube

	
Ring magnet Part no. 402 316	Ring magnet Part no. 403 974
Material: PA ferrite coated Weight: ca. 13 g Operating temperature: -40...+100 °C Surface pressure: 20 N/mm ²	Material: NdFeB Weight: ca. 20 g Operating temperature: -40...+100 °C Surface pressure: 20 N/mm ²

M12 Flange

Testkits

			
M12 Flange (spare part) Part no. 253 769	Testkit Analog Part no. 280 618	Testkit Digital Part no. 254 267	Testsoftware Digital Part no. 625 129
	<ul style="list-style-type: none"> MH-Series analog / PWM Tester 12 VDC battery charger with adapter (adapter main plug EU, adapter main plug UK) cable with M12 connector cable with pigtailed wires carrying case 	<ul style="list-style-type: none"> USB CAN-Modul Kit: <ul style="list-style-type: none"> USB CAN-Modul USB CAN-Modul Utility CD (driver & manual) USB cable cable with MTS M12 connector and RS232 connector cable with RS232 connector carrying case 12 VDC power supply 	Software for MH Digital

Order information:
For complete package please
order both part numbers.

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